Pointers

Chapter 8



Decision Procedures An Algorithmic Point of View

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Outline

- 1 Introduction
 - Pointers and Their Applications
 - Dynamic Memory Allocation
 - Analysis of Programs with Pointers
- **2** A Simple Pointer Logic
 - Syntax
 - Semantics
 - Axiomatization of the Memory Model
 - Adding Structure Types
- 3 Modeling
 - Lists
 - Trees
- 4 Using the Semantic Translation
 - Applying the Memory Model Axioms
 - Pure Variables
 - Partitioning the Memory

Pointer: a program variable that refers to some other program construct

This other construct may be

- another variable, including a pointer,
- a function or method.

• Pointers to other variables allow code fragments to operate on different sets of data

• This avoids inefficient copying of data

• Pointers enable dynamic data structures

• But: Many bugs relate to the (ab-)use of pointers

• Memory cells of a computer have *addresses*, i.e., each cell has a unique number

• The value of a pointer is such a number

• memory model: the way the memory cells are addressed

Definition (Our Memory Model)

- Set of addresses A is a subinterval of the integers $\{0,\ldots,N-1\}$
- Each address corresponds to a memory cell that is able to store one data word.
- The set of data words is denoted by *D*.
- Memory valuation $M: A \longrightarrow D$

(this is a continuous, uniform address space)

A variable may require more than one data word to be stored in memory $% \left({{{\mathbf{x}}_{i}}} \right)$

Examples:

- structs,
- arrays,
- double-precision floating-point

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Let $\sigma(v)$ with $v \in V$ denote the size (in data words) of v.

Let V denote the set of variables.

Definition (memory layout)

A memory layout $L: V \longrightarrow A$ is a mapping from V to an address A. The address of $v \in V$ is also called the memory location of v.

- The memory locations of the statically allocated variables are usually *non-overlapping*
- The memory layout is not necessarily continuous (e.g., due to alignment restrictions)

```
int var_a, var_b, var_c;
struct { int x; int y; } S;
int array[4];
int *p = &var_c;
int main() {
 *p=100;
}
```



• There is an area of memory (called heap) for objects that are created at run time

- A library maintains a list of the memory regions that are unused
- Some function allocates a memory region of a given size and returns a pointer to it
 - malloc() in C,
 - **new** in C++, C#, and Java.

Program analysis tools often need to reason about pointers

```
void f(int *sum) {
 *sum = 0;
 for(i=0; i<10; i++)
 *sum = *sum + array[i];
}</pre>
```

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```
void f(int *sum) {
 *sum = 0;

for(i=0; i<10; i++)
 *sum = *sum + array[i];
}</pre>
```

- This program does not obey the obvious specification if the address held by sum is equal to the address of i
- Aliasing not anticipated by the programmer is a common source of problems

Definition (Pointer Logic) Syntax:

formula	:	$formula \land formula ~ ~ \neg formula ~ ~ (formula) ~ ~ atom$
atom	:	$pointer = pointer \mid term = term \mid$
		$pointer \ < \ pointer \ \mid term \ < \ term$
pointer	:	$pointer - identifier \mid pointer + term \mid (pointer) \mid$
		& identifier $ \& * pointer * pointer $ NULL
term	:	$identifier \mid * pointer \mid term \ op \ term \mid (term) \mid$
		integer - constant identifier [term]
op	:	+ -

Warning: = is equality here, not assignment

Decision Procedures – Pointers

Let $p, \ q$ denote pointer identifiers, and let $i, \ j$ denote integer identifiers.

The following formulas are well-formed according to the grammar:

- *(p+i) = 1,
- $\bullet \ \ast (p+\ast p)=0\text{,}$
- $p = q \wedge *p = 5$,
- * * * * * p = 1,
- p < q.

The following formulas are not permitted by the grammar:

- p+i,
- p = i,
- $\bullet \ \ast (p+q) \text{,}$
- *1 = 1,
- p < i.

• We define the semantics by referring to a specific memory layout L and a specific memory valuation M.

• Pointer logic formulas are predicates on M, L pairs

• We obtain a reduction to integer arithmetic and array logic

We define a semantics using the function

$$\llbracket \cdot \rrbracket : \mathcal{L}_P \longrightarrow \mathcal{L}_D$$

 \mathcal{L}_P : language of pointer expressions \mathcal{L}_D : expressions over variables with values from D Defined recursively.

Boolean connectives:

$$\begin{bmatrix} f_1 \wedge f_2 \end{bmatrix} = \begin{bmatrix} f_1 \end{bmatrix} \wedge \begin{bmatrix} f_2 \end{bmatrix} \\ \begin{bmatrix} \neg f \end{bmatrix} = \neg \begin{bmatrix} f \end{bmatrix}$$

Predicates:

$$\begin{bmatrix} p_1 = p_2 \end{bmatrix} = \begin{bmatrix} p_1 \end{bmatrix} = \begin{bmatrix} p_2 \end{bmatrix} \text{ whe} \\ \begin{bmatrix} p_1 < p_2 \end{bmatrix} = \begin{bmatrix} p_1 \end{bmatrix} < \begin{bmatrix} p_2 \end{bmatrix} \text{ whe} \\ \begin{bmatrix} t_1 = t_2 \end{bmatrix} = \begin{bmatrix} t_1 \end{bmatrix} = \begin{bmatrix} t_2 \end{bmatrix} \text{ whe} \\ \begin{bmatrix} t_1 < t_2 \end{bmatrix} = \begin{bmatrix} t_1 \end{bmatrix} < \begin{bmatrix} t_2 \end{bmatrix} \text{ whe} \\ \end{bmatrix}$$

where p_1 , p_2 are pointer expressions where p_1 , p_2 are pointer expressions where t_1 , t_2 are terms where t_1 , t_2 are terms

Non-pointer terms:

Pointer-related expressions:

$$\begin{split} \llbracket p \rrbracket &= M[L[p]] & \text{where } p \text{ is a pointer identifier} \\ \llbracket p+t \rrbracket &= \llbracket p \rrbracket + \llbracket t \rrbracket & \text{where } p \text{ is a pointer expression, } t \text{ is a term} \\ \llbracket \& v \rrbracket &= L[v] & \text{where } v \in V \text{ is a variable} \\ \llbracket \& * p \rrbracket &= \llbracket p \rrbracket & \text{where } p \text{ is a pointer expression} \\ \llbracket \text{NULL} \rrbracket &= 0 \\ \llbracket * p \rrbracket &= M[\llbracket p \rrbracket] & \text{where } p \text{ is a pointer expression} \end{split}$$

• A pointer p points to a variable x if M[L[p]] = L[x]

• Shorthand: $p \hookrightarrow z$ for *p = z

Warning: the meaning p + i does not depend on the type of p

*((&a) + 1) = a[1]

The definition expands as follows:

[[*((&a)+1) = a[1]]]

*((&a) + 1) = a[1]

The definition expands as follows:

 $\llbracket \ast ((\&a)+1) = a[1] \rrbracket \iff \llbracket \ast ((\&a)+1) \rrbracket = \llbracket a[1] \rrbracket$

*((&a) + 1) = a[1]

The definition expands as follows:

$$\llbracket *((\&a) + 1) = a[1] \rrbracket \iff \llbracket *((\&a) + 1) \rrbracket = \llbracket a[1] \rrbracket \\ \iff M[\llbracket (\&a) + 1 \rrbracket] = M[L[a] + \llbracket 1 \rrbracket]$$

*((&a) + 1) = a[1]

The definition expands as follows:

$$\begin{split} \llbracket * ((\&a) + 1) &= a[1] \rrbracket \iff & \llbracket * ((\&a) + 1) \rrbracket &= \llbracket a[1] \rrbracket \\ \iff & M[\llbracket (\&a) + 1 \rrbracket] &= M[L[a] + \llbracket 1 \rrbracket] \\ \iff & M[\llbracket \&a \rrbracket + \llbracket 1 \rrbracket] = M[L[a] + 1] \end{split}$$

*((&a) + 1) = a[1]

The definition expands as follows:

$$\begin{split} \llbracket *((\&a) + 1) &= a[1] \rrbracket \iff & \llbracket *((\&a) + 1) \rrbracket &= \llbracket a[1] \rrbracket \\ \iff & M[\llbracket(\&a) + 1] \rrbracket &= M[L[a] + \llbracket 1] \rrbracket \\ \iff & M[\llbracket\&a] \rrbracket + \llbracket 1] \rrbracket &= M[L[a] + 1] \\ \iff & M[L[a] + 1] = M[L[a] + 1] \end{split}$$

The last formula is obviously valid.

Decision Procedures – Pointers

The translated formula must evaluate to true for any L and M!

The following formula is not valid:

 $*p = 1 \longrightarrow x = 1$

For $p \neq \&x$, this formula evaluates to false.

• It is possible to exploit assumptions made about the memory model.

• Depends highly on the architecture!

• Here: we formalize properties that *most* architectures comply with.

On most architectures, the following two formulas are valid:

- $\textcircled{2} \& x \neq \& y$

(1) translates into $L[x] \neq 0$ and relies on the fact that no object has address 0.

(2) relies on non-overlapping addresses

Memory Model Axiom ("No object has address 0")

 $\forall v \in V. \ L[v] \neq 0$

Decision Procedures – Pointers

How do we address (2)?

Suggestion:

$$\forall v_1, v_2 \in V. \ v_1 \neq v_2 \longrightarrow L[v_1] \neq L[v_2]$$

The following two conditions together are stronger:

Memory Model Axiom ("Objects have size at least one") $\forall v \in V. \ \sigma(v) \geq 1$

Memory Model Axiom ("Objects do not overlap")

$$\forall v_1, v_2 \in V. \ v_1 \neq v_2 \longrightarrow \{L[v_1], \dots, L[v_1] + \sigma(v_1) - 1\} \cap \\ \{L[v_2], \dots, L[v_2] + \sigma(v_2) - 1\} = \emptyset .$$

Some code relies on additional, architecture-specific guarantees, e.g.,

- byte ordering
- endianness,
- alignment,
- structure layout.

Some program analysis tools allow adding such rules.

• Convenient way to implement data structures

• We add this as a syntactic extension

• Notation: s.f to denote the value of the field f in the structure s

Mapping to Array Types

- Each field of the structure is assigned a unique offset: o(f)
- Meaning of *s*.*f*:

$$s.f \doteq *((\&s) + o(f))$$

• Following PASCAL and ANSI-C syntax:

$$p \rightarrow f \doteq (*p).f$$

• Adopted from separation logic:

$$p \hookrightarrow a, b, c, \dots \stackrel{:}{=} \begin{cases} *(p+0) = a & \land \\ *(p+1) = b & \land \\ *(p+2) = c & \dots \end{cases}$$

• Simplest dynamically allocated data structure

• Realized by means of a structure type that contains fields for a next pointer



$$\begin{array}{cccc} p \hookrightarrow & `t', p_1 \\ \wedge & p_1 \hookrightarrow & `e', p_2 \\ \wedge & p_2 \hookrightarrow & `x', p_3 \\ \wedge & p_3 \hookrightarrow & `t', \text{NULL}. \end{array}$$

Decision Procedures – Pointers

32

Define a recursive shorthand for the *i*-th member of a list:

We use 'n' as the next pointer field.

Now define the shorthand list(p, l):

 $list(p, l) \doteq list-elem(p, l) = NULL$

A linked list is cyclic if the pointer of the last element points to the first one:



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Would this work?

 $\mathsf{my-list}(p,l) \ \doteq \ \mathsf{list-elem}(p,l) = p \;.$

Unfortunately, the following satisfies my-list(p, 4):



 \rightarrow need to rule out sharing

Define a shorthand 'overlap' as follows:

```
\mathsf{overlap}(p,q) \doteq p = q \lor p + 1 = q \lor p = q + 1
```

Use to state that all list elements are pairwise disjoint:

Grows quadratically in l!



Goal: model binary search tree

- Pointer to the left-hand child: l
- $\bullet\,$ Pointer to the right-hand child: r

Idea:

$$\begin{array}{l} (n.l \neq \text{NULL} \longrightarrow n.l \rightarrow x < n.x) \\ \wedge \quad (n.r \neq \text{NULL} \longrightarrow n.r \rightarrow x > n.x) \; . \end{array}$$

Idea: $(n.l \neq \text{NULL} \longrightarrow n.l \Rightarrow x < n.x)$ $\land \quad (n.r \neq \text{NULL} \longrightarrow n.r \Rightarrow x > n.x) .$

Not strong enough for O(h) lookup!

Let us first define the transitive closure of a relation R:

$$\begin{array}{rcl} \mathcal{T}C^{1}_{R}(p,q) &\doteq & R(p,q) \\ \mathcal{T}C^{i}_{R}(p,q) &\doteq & \exists p'. \ \mathcal{T}C^{i-1}_{R}(p,p') \wedge R(p',q) \\ \mathcal{T}C(p,q) &\doteq & \exists i. \ \mathcal{T}C^{i}_{R}(p,q) \end{array}$$

Now define a predicate tree-reach(p, q):

$$\begin{array}{lll} \mathsf{tree-reach}(p,q) &\doteq & p \neq \mathrm{NULL} \land q \neq \mathrm{NULL} \land \\ & (p = q \lor p {\rightarrow} l = q \lor p {\rightarrow} r = q) \end{array}$$

Use the transitive closure:

$$\mathsf{tree-reach}^{*}(p,q) \iff \mathsf{TC}_{\mathsf{tree-reach}(p,q)}$$

New definition:

$$\begin{array}{l} (\forall p. \ {\sf tree-reach}^{\ast}(n.l,p) \longrightarrow p {\rightarrow\!\!\!\!>} x < n.x) \\ \wedge \quad (\forall p. \ {\sf tree-reach}^{\ast}(n.r,p) \longrightarrow p {\rightarrow\!\!\!\!>} x > n.x) \ . \end{array}$$

$\llbracket \cdot \rrbracket$ is a decision procedure!

• Define $\varphi' \doteq \llbracket \varphi \rrbracket$

2 Pass φ' to procedure for integers and arrays

Let x be a variable, and p be a pointer.

$$p = \& x \land x = 1 \longrightarrow *p = 1$$

Let x be a variable, and p be a pointer.

$$p = \& x \land x = 1 \longrightarrow *p = 1$$

Use semantic definition:

$$\begin{split} \llbracket p &= \&x \wedge x = 1 \longrightarrow *p = 1 \rrbracket \\ & \longleftrightarrow \quad \llbracket p = \&x \rrbracket \wedge \llbracket x = 1 \rrbracket \longrightarrow \llbracket *p = 1 \rrbracket \\ & \Leftrightarrow \quad \llbracket p \rrbracket = \llbracket \&x \rrbracket \wedge \llbracket x \rrbracket = 1 \longrightarrow \llbracket *p \rrbracket = 1 \\ & \longleftrightarrow \quad M[L[p]] = L[x] \wedge M[L[x]] = 1 \longrightarrow M[M[L[p]]] = 1 \;. \end{split}$$

The last formula is obviously valid.

Example II

$$\begin{split} \llbracket p \hookrightarrow x \longrightarrow p = \& x \rrbracket \\ \iff & \llbracket p \hookrightarrow x \rrbracket \longrightarrow \llbracket p = \& x \rrbracket \\ \iff & \llbracket *p = x \rrbracket \longrightarrow \llbracket p \rrbracket = \llbracket \& x \rrbracket \\ \iff & \llbracket *p \rrbracket = \llbracket x \rrbracket \longrightarrow M[L[p]] = L[x] \\ \iff & M[M[L[p]]] = M[L[x]] \longrightarrow M[L[p]] = L[x] \end{split}$$

44

Example II

$$\begin{split} \llbracket p \hookrightarrow x \longrightarrow p &= \& x \rrbracket \\ \iff & \llbracket p \hookrightarrow x \rrbracket \longrightarrow \llbracket p &= \& x \rrbracket \\ \iff & \llbracket *p &= x \rrbracket \longrightarrow \llbracket p \rrbracket = \llbracket \& x \rrbracket \\ \iff & \llbracket *p \rrbracket = \llbracket x \rrbracket \longrightarrow M[L[p]] = L[x] \\ \iff & M[M[L[p]]] = M[L[x]] \longrightarrow M[L[p]] = L[x] \end{split}$$

Counterexample:

$$L[p] = 1, L[x] = 2, M[1] = 3, M[2] = 10, M[3] = 10$$



What if the formula relies on a memory model axiom?

Example:

$$\sigma(x) = 2 \longrightarrow \& y \neq \& x + 1$$

The semantic translation yields:

$$\sigma(x) = 2 \longrightarrow L[y] \neq L[x] + 1$$

This needs the no-overlapping axiom:

 $\{L[x],\ldots,L[x]+\sigma(x)-1\}\cap\{L[y],\ldots,L[y]+\sigma(y)-1\}=\emptyset$

Transform into linear arithmetic over the integers as follows:

 $(L[x] + \sigma(x) - 1 < L[y]) \lor (L[x] > L[y] + \sigma(y) - 1)$

② Using
$$\sigma(x) = 2$$
 and $\sigma(y) \ge 1$:
 $(L[x] + 1 < L[y]) \lor (L[x] > L[y])$

(3) Now strong enough to imply $L[y] \neq L[x] + 1$

$$\begin{split} \llbracket x = y \longrightarrow y = x \rrbracket \\ \iff \quad \llbracket x = y \rrbracket \longrightarrow \llbracket y = x \rrbracket \\ \iff \quad M[L[x]] = M[L[y]] \longrightarrow M[L[y]] = M[L[x]] \;. \end{split}$$

Unnecessary burden for the array decision procedure!

$$\begin{split} \llbracket x = y \longrightarrow y = x \rrbracket \\ \iff \quad \llbracket x = y \rrbracket \longrightarrow \llbracket y = x \rrbracket \\ \iff \quad M[L[x]] = M[L[y]] \longrightarrow M[L[y]] = M[L[x]] \;. \end{split}$$

Unnecessary burden for the array decision procedure!

Should have done:

 $x = y \longrightarrow y = x$

Obvious idea:

if the address of a variable x is not referred to, translate it to a new variable Υ_x instead of M[L[x]]

Observation: the run time of a decision procedure for array logic depends on the number of different expressions that are used to index a particular array

Example

$$*p = 1 \land *q = 1$$

This is

$$M[\Upsilon_p] = 1 \wedge M[\Upsilon_q] = 1$$

- p and q might alias
- But there is no reason why they have to!
- Let's assume they don't!

We partition M into M_1 and M_2 :

$$M_1[\Upsilon_p] = 1 \land M_2[\Upsilon_q] = 1$$

- This increases the number of array variables
- But: the number of different indices per array decreases!
- Typically improves performance

Cannot always be applied:

$$p = q \longrightarrow *p = *q$$

- Obviously valid
- If we partition as before, the translated formula is no longer valid:

$$\Upsilon_p = \Upsilon_q \longrightarrow M_1[\Upsilon_p] = M_2[\Upsilon_q]$$

- Deciding if the optimization is applicable is in general as hard as deciding φ itself
- $\rightarrow\,$ Do an approximation based on a syntactic test

Definition

- Deciding if the optimization is applicable is in general as hard as deciding φ itself
- \rightarrow Do an approximation based on a syntactic test

Two pointer expressions $p \mbox{ and } q$ are related if both $p \mbox{ and } q$ are used inside the same relational expression

Write $p \approx q$ for TC_{related}

Partition according to \approx !